

MCx-Lx-xxxAx-8.09

(12-24 VDC; Linear Drive; 4-20 mA Control)

USER MANUAL

Contents

INSTALLATION	2
Mounting	2
Wiring	2
Power Supply and Current Draw	3
Control Signal and Feedback	3
OPERATION	4
DIP switches	4
Controlling the Actuator	4
<i>Changing the stroke length</i>	5
Thrust Settings	6
<i>Speed and Thrust Details</i>	6
Signal Loss and Calibration	7
Troubleshooting	8
ACTUATOR DIMENSIONS	9
PART NUMBER BREAKDOWN	10
LABEL BREAKDOWN	11

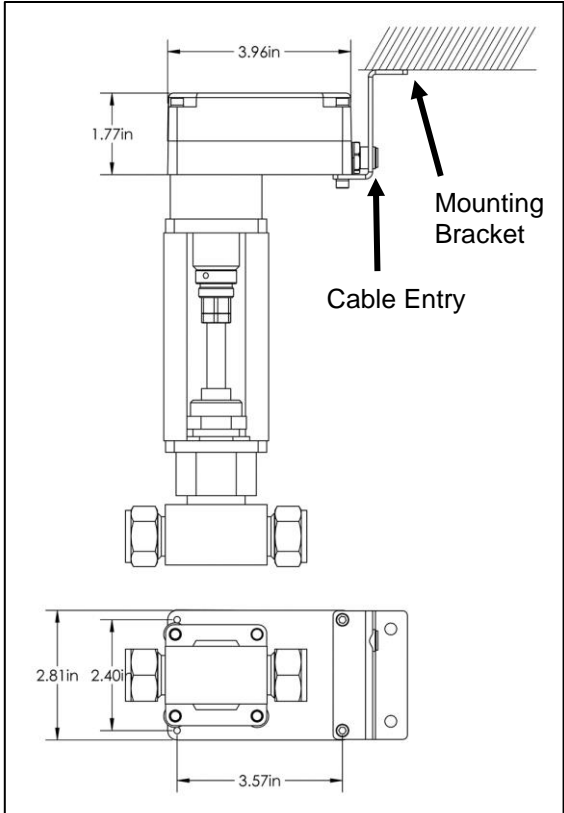


INSTALLATION

Mounting

In most cases, the actuator must be mounted and supported as shown in the image to the right. The mounting bracket is not supplied by Hanbay.

Exceptionally, the actuator may be suspended on the tubing itself but ONLY if the application is vibration free and the tubing is minimum 1/4" dia. stainless.



Wiring

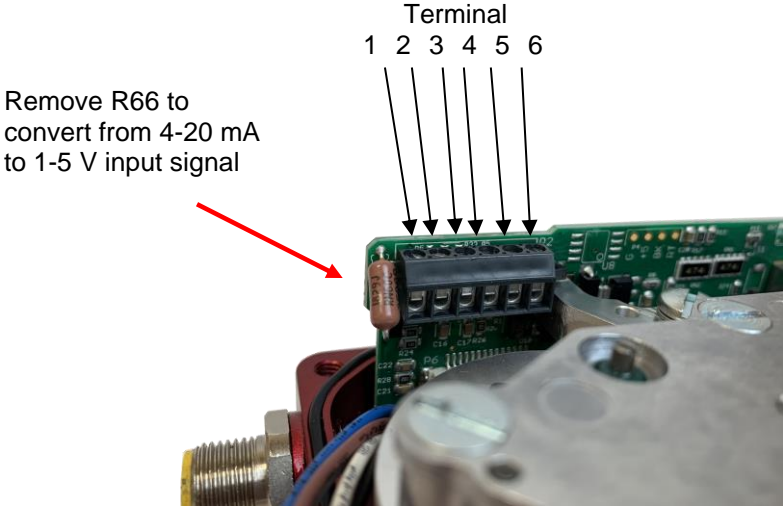
The actuator comes standard with a Turck 5 position connector and a 20' cable with plug. Cut the cable to the length required and then connect according to the following wire color schematic:

Wire color schematic for "Turck5" cable:

Pin	Colour	Function
6	White	+24 VDC
5	Black	Power Gnd.
4	Grey	Output Signal (4-20 mA)*
3		Not connected
2	Brown	Isolated** Input Signal Gnd.
1	Blue	Isolated** Input + Signal (4-20 mA)

* "feedback" available in MCx-Lx-xxxAF version of actuator only.
** "isolated" available in MCx-Lx-xxxAI and xxxAF versions of actuator only.

If the Turck cable is not included in your actuator, connect the wires to the corresponding pins on the terminal block as indicated in the schematic:



Power Supply and Current Draw

The MCx-Lx-xxxAx may be connected to voltages ranging within 12-24 VDC.

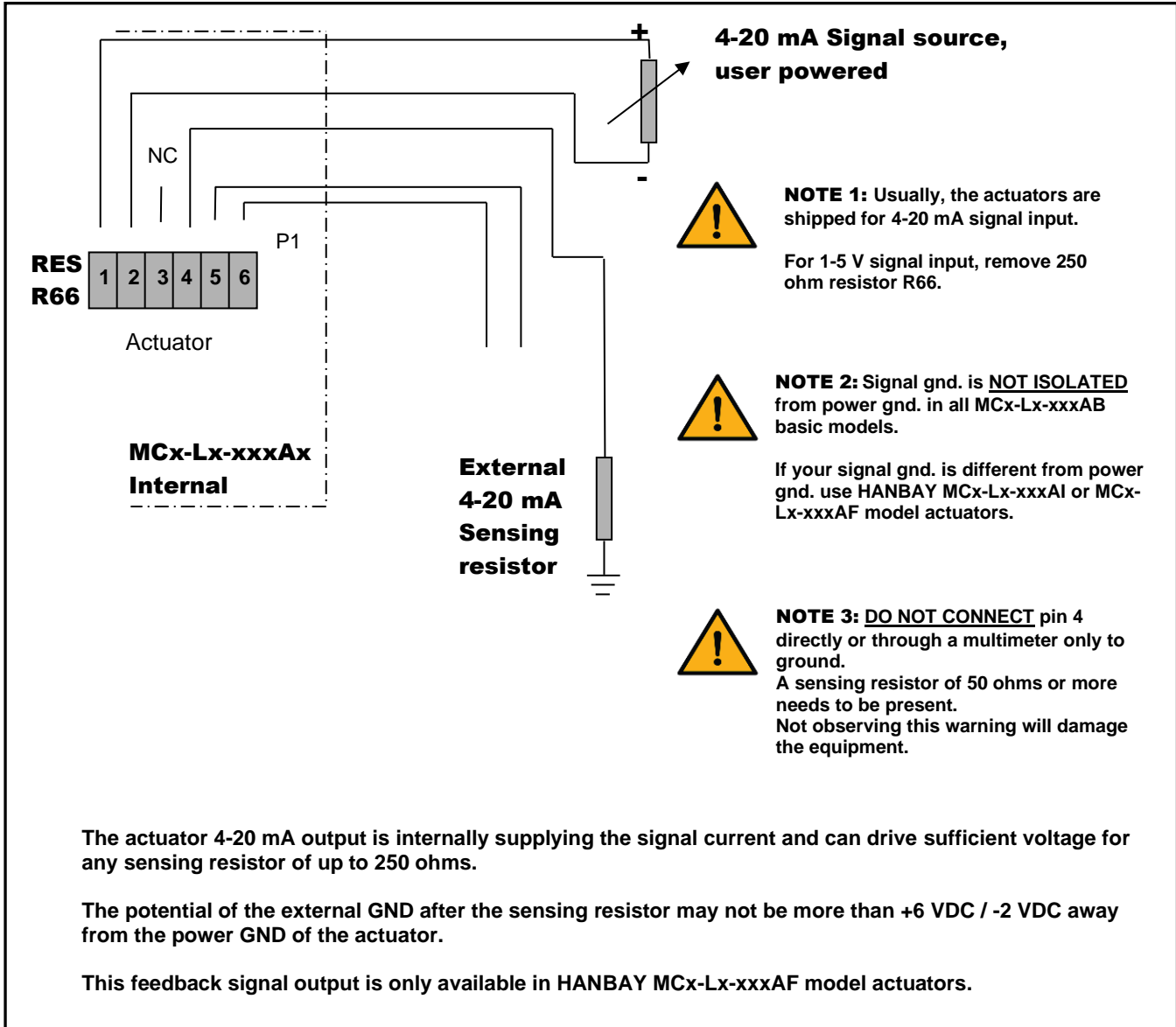
The current draw will range from minimum 100 mA to maximum 3 A while the actuator is active. When not moving, the actuator draws approx. 50 mA.



Note: Digital potentiometer functionality is disabled for supply voltages below 18 VDC, so the actuator position will not be retained on power-loss, on power-up the actuator will need to be re-zeroed every time.

Control Signal and Feedback

Locate the correct connection terminals/wires as shown on the previous page, then connect your input signal on positions 1 and 2 (blue and brown wires) as shown below. Feedback, if applicable is connected to position 4 (grey wire).



OPERATION

DIP switches

The DIP switches allow you to change the settings on your actuator. To flip a switch, gently use a small flat-head screwdriver.

See chart on next page for DIP switch functionality.



In this example DIPs 1, 2, 5 and 12 are on.

DIP	Function
1	Speed: Choose how quickly the actuator will turn the drive wheel. See p. Error! Bookmark not defined..
2	Not used.
3	Not used.
4	Stroke: The actuator usually ships from the factory with the recommended stroke for the valve. However, this value can be changed. Turning on a switch will add a specific amount of travel to the actuator's stroke.
5	See p.5 for relation between position of the DIP switches and stroke.
6	
7	
8	
9	Signal loss: See p. Error! Bookmark not defined..
10	Seating thrust force: Set how much torque the actuator exerts on the valve lever during the calibration (finding valve seat) procedure. See p. Error! Bookmark not defined..
11	
12	Direction/Calibration: Toggle switch on and off while powered to re-calibrate actuator (find valve seat). Also sets direction in which the actuator will open and close. See p. Error! Bookmark not defined..

Example: The MCM model actuator turns clockwise when the signal is decreased with DIP 12 in the OFF position. Putting DIP 12 in the ON position will cause counterclockwise turning for a decrease in signal. For changes in DIP 12 position to take effect, the power to the actuator must be cycled.

Controlling the Actuator

The 4-20 mA (or 1-5 V) input signal is proportional to the stroke of the valve.

Example:

You have an actuator with TPI=16 (standard). Valve stroke is 0.75". You wish to move the actuator so the valve's position is 0.122" above the closed position.

$$0.122/0.750=0.163 \qquad 20mA-4mA= \text{range of } 16mA$$

$$0.163*16=2.608. \qquad 2.608+4mA=6.608mA$$

To get 0.122" above the closed position, supply signal of 6.608mA to the actuator.

Changing the stroke length

The standard HANBAY linear actuator (MCx-L1-xxxAx models) has a maximal stroke of 1", and has 16 threads per inch (TPI). With the DIP switch settings, the actual stroke can be adjusted between 0.0625" and 1" in 1/16" increments, as indicated in the table below.

Non-standard MCx-L2-xxxAx models have 8 TPI instead. The stroke of these actuator models can be adjusted between 0.125" and 1" in 1/8" increments.

Additional non-standard models with a maximal stroke of 2" & 4" are also available. For such models, use the same DIP switch settings as indicated below, and multiply the stroke by 2 or 4 (for both 16 & 8 TPI models).

16 TPI (MCx-L1 models):				
Total Stroke (DIP 4 = 0)	DIP 5	DIP 6	DIP 7	DIP 8
<i>reserved</i>	0	0	0	0
0.0625"	0	0	0	1
0.1250"	0	0	1	0
0.1875"	0	0	1	1
0.2500"	0	1	0	0
0.3125"	0	1	0	1
0.3750"	0	1	1	0
0.4375"	0	1	1	1
0.5000"	1	0	0	0
0.5625"	1	0	0	1
0.6250"	1	0	1	0
0.6875"	1	0	1	1
0.7500"	1	1	0	0
0.8125"	1	1	0	1
0.8750"	1	1	1	0
0.9375"	1	1	1	1

8 TPI (MCx-L2 models):				
Total Stroke (DIP 4 = 0)	DIP 5	DIP 6	DIP 7	DIP 8
<i>reserved</i>	0	0	0	0
0.125"	0	0	0	1
0.250"	0	0	1	0
0.375"	0	0	1	1
0.500"	0	1	0	0
0.625"	0	1	0	1
0.750"	0	1	1	0
0.875"	0	1	1	1
1.00"	1	0	0	0

* Turn on DIP 4 **only** for 1.000" stroke.



WARNING: The stroke should not be set to exceed 1", otherwise the unit will stall. Also be sure that the stroke of the actuator is **LESS** than the stroke of the valve. The actuator should not stop itself on a fully opened valve. It can damage the valve, and the actuator will lose its position.

Thrust Settings

To accommodate different valves and other applications with different torque requirements, the actuator can be set to apply different amounts of force on the valve stem when in the seating mode.

During normal operation, the actuator will try to reach the speed set by DIP 1 and DIP 2. It will use 100% thrust to try and reach the selected speed, regardless of the positions of DIP 10 and DIP 11. Current draw is limited to 3 A regardless of settings.

**Seating power settings:
(when operating at 24V)**

DIP 10	DIP 11	Power
OFF	OFF	16%
OFF	ON	33%
ON	OFF	66%
ON	ON	100%

To deal with sticking valves, at the beginning of the first reversing movement after the seating (“zeroing”) of the valve, the actuator will apply double the power set by DIP 10 and DIP 11 (up to 100% power.) This “pull out” function is always enabled.



WARNING: High power settings can supply enough thrust to damage your valve. Please be cautious, especially when using the 100% power setting.



NOTE: 66% setting and 100% setting require voltage supply minimum values as follows:

- Supply voltage needs to be min 14 VDC for 66% setting
- Supply voltage needs to be 16 VDC for 100% setting
- When operating above 20 VDC and 66% power, Duty cycle is reduced to 50% - 25% maximum. At these levels, the electronics produce more heat which must be dissipated (depending on environmental temperature)

Speed and Thrust Details

The maximum speed of the actuator can be set by using the first two positions of the DIP switch selector. As a result of this setting, the actuator will limit the maximum speed. The tables below show the time required for 1” of travel.

The seating thrust depends on the voltage provided in the power connection and on the seating power settings on DIP 10, 11 as shown below. The values shown are for a 24 VDC power connection.

MCL-Lx-xxxAx Actuators

Speed:			
DIP 1	DIP 2	Seconds per inch	
		8 TPI	16 TPI
OFF	OFF	63	120
OFF	ON	32	64
ON	OFF	20	38
ON	ON	13	26

Thrust:			
DIP 10	DIP 11	Seating Thrust (lbs)	
		8 TPI	16 TPI
OFF	OFF	37	13
OFF	ON	83	44
ON	OFF	149	88
ON	ON	180	138
Running Thrust		200	175

NOTE: If actuator is MCJ-Lx-xxxAx, divide thrust values by 3.
NOTE: If actuator is powered by 12 VDC, divide thrust values by 2.
To convert lbs to N, divide by 4.5.

MCM-Lx-xxxAx Actuators

Speed:			
DIP 1	DIP 2	Seconds per inch	
		8 TPI	16 TPI
OFF	OFF	189	360
OFF	ON	96	192
ON	OFF	60	114
ON	ON	40	78

Thrust:			
DIP 10	DIP 11	Seating Torque (lbs)	
		8 TPI	16 TPI
OFF	OFF	110	35
OFF	ON	245	128
ON	OFF	445	256
ON	ON	535	400
Running Thrust		600	517
<small>NOTE: If actuator is MCK-Lx-xxxAx, divide thrust values by 3. NOTE: If actuator is powered by 12 VDC, divide thrust values by 2. To convert lbs to N, divide by 4.5.</small>			

Signal Loss and Calibration

1. **For actuators that are not connected to a UPS** (Uninterruptible Power Supply), the loss of signal will be simultaneous with power loss. Consequently, the actuator will not be able to move anywhere. In the shutdown process, the actual position is automatically saved to the internal EEPROM. [This saving of the position only happens for min. 18 VDC supplies] When power is restored, the actuator will “know” its location and will simply start to follow the signal as received.



IF YOU HAVE TO turn the actuator manually when its power is turned off, it will lose its position, and it will need to be re – zeroed (as described in sub-section 3).

2. **For actuators that are connected to a UPS** the behavior on signal loss can be set as follows:

Normal position of DIP 9: OFF

With DIP 9 in the off position, the actuator will ignore the signal if it is lost (i.e.: if the signal falls below 0.700 V or 2.80 mA) and simply remain in its current position.

Note: if the sensing resistor R66 is removed (for 1-5 V input signals), we recommend placing a 10K resistor between signal and signal GND.

Predetermined signal loss position DIP 9: ON

With DIP 9 in the on position, the actuator will move to a predetermined position when the signal is lost (i.e.: if the signal falls below 2.80 mA or 0.700 V).

Setting of the predetermined signal loss position:

- a.- turn DIP 9 to the “off” position
- b.- re-zero the actuator by sending and holding an input signal between 2.80 and 4.16 mA (0.700 and 1.04 V) wait until the device is re-zeroed, (i.e.: valve is closed)
- c.- by varying the input signal, move the actuator to the position that is going to be the predetermined signal loss position.
- d.- switch DIP 9 to the “on” position. The current actuator position will be saved as the default signal loss position. (The default signal position is an absolute actuator position, not a signal value.)

3. **Re-zeroing the actuator and initiating calibration routine:**

The actuator will re-zero when the input signal is between 2.80 and 4.16 mA (0.700 and 1.04 V). It will turn clockwise until the actuator has reached the fully closed position of the valve.

If the valve is removed for any reason, the calibration routine must be initiated on the actuator manually. This is done by toggling DIP 12 (switch position, then back to the original position) while the actuator is powered. This will prevent damage to the valve.

If you need to re-zero in the opposite direction (i.e.: for pressure regulators, which typically go to the “top” fully open position at 4 mA) change the setting of DIP 12 and cycle power.

4. **Feedback calibration: [MCx-Lx-xxxAF model actuators only]**

The current feedback will be calibrated from the factory.

To re-calibrate the feedback:

- a.- Turn off the actuator and disconnect the feedback and input signals. If possible, remove the actuator from the valve.
- b.- Connect the feedback signal to the signal input. Also connect the power and signal grounds.
- c.- Power up the actuator with this “signal loop-back” setup.
- d.- Short SP1. It will automatically run a special routine to calibrate the feedback signal to the signal input. The whole process takes about 1.5 seconds.
- e.- turn off the power and reconnect the actuator as normal.

Troubleshooting

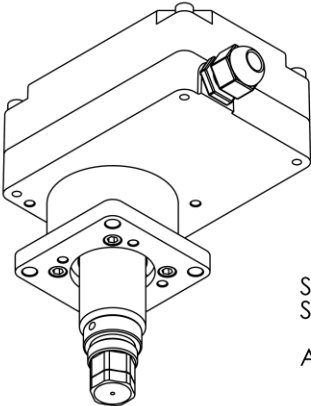
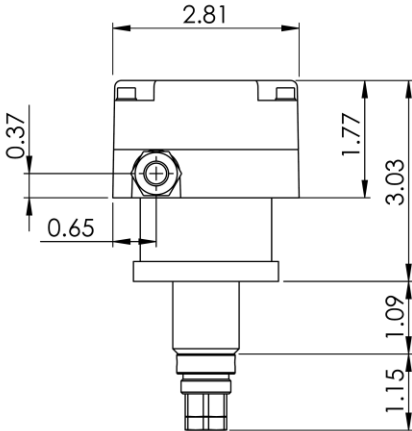
Upon noticing a problem, your first step should almost always be to recalibrate the actuator by toggling DIP 12 while the actuator is powered. This alone can solve basic problems. See sub-section 3 above for more details.

If the actuator does not move, try following these steps:

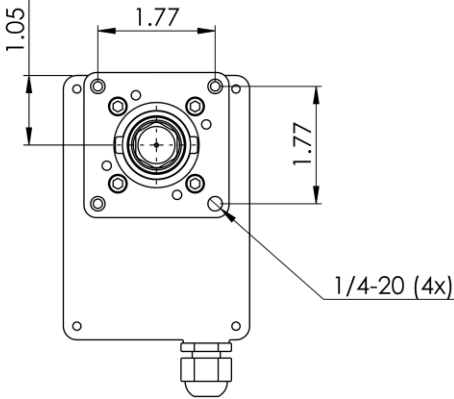
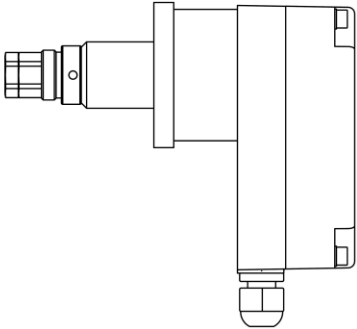
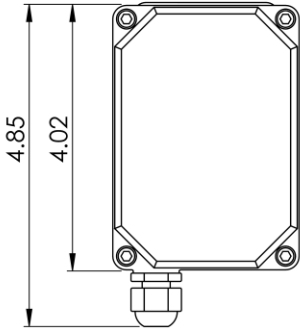
- 1) Re-calibrate the actuator. This will move the actuator regardless of what signal it is receiving.
- 2) A sticking valve may be the problem. Remove the valve from the actuator, and re-test the actuator.
- 3) Remove power. Re-check the wiring and the power/signal apparatus. Power actuator and re-calibrate. If the problem persists, please call Hanbay for technical support.

ACTUATOR DIMENSIONS

MCx-Lx-xxxAx models



Stroke length 1"
Shown in extended position
Additional options: 2" & 4"



PART NUMBER BREAKDOWN

Full Hanbay Part Number: **M** **C** - **Lx** - **Ax** -

	Base Enclosure	Continuous or Discrete	Gear Train	Special Options	Enclosure Options	Wiring	Thermal Management	PCB	Mounting Kit	Valve Part Number
M			-	-					-	Valve Manufacturer's Part # / CU #
M	M-Series									0 No Valve or Mounting Kit 1 Mounting Kit, Customer Supplies Valve, does not send valve to Hanbay 2 Mounting Kit, Customer Supplies Valve, sends valve to Hanbay 3 Mounting Kit, Hanbay Provides Valve
C	Continuous									
D	Discrete									
J	Extra Low Torque									
K	M gear train w/ low torque motor									
L	Low Torque									
M	Medium Torque									
H	High Torque (Add. Gear Stage)									
F	F-Gear Stage (Add. Gear Stage)									
										0 No Option H Internal Heater F External Fan
										0 Cable Gland (Specify Cable & length at added cost) 4 Custom Dual Gauge Cable, 10ft. 5 TURCK 5 Position Connector w. 20' Cable and Plug 6 TURCK 6 Position Connector w. 20' Cable and Plug 7 TURCK 5 Position Connector Only 8 TURCK 8 Position Connector w. 20' Cable and Plug (Special)
										0 Standard Red Alloy Enclosure M Manual Override S Stainless Steel Enclosure N Black Alloy Enclosure
										0 No Special Options HT High Temperature Kit B Battery Backup G G-Stage Gate Valve (MCM or MCL) L1 Linear 16 TPI L2 Linear 8 TPI M Manual Override (When M in Enclosure Option is not usable) AC 110VAC Power Supply S Spring Return RS Reverse Spring Return TS Top Stop BS Bottom Stop

LABEL BREAKDOWN

Firmware Version

AF-1.05 } MM = Multiturn
 AB-1.05 } MML = Multiturn Low Torque
 AS-1.05 } MMUL = Multiturn Extra Low Torque
 } QM = Quarter turn
 } QM97 = Quarter turn 97°
 DT-2.01
 DC-2.01
 DT-4.06 (Obsolete since 2019)
 M-Dx V2.31

Actuator Supply Voltage

12-24 VDC @ 3.0 A or
 110-240 VAC @ 1.5 A

Circuit Board Version

Ax-8.09
 Dx-10.31
 Dx-4.10 (Obsolete since 2019)
 Px-10.3

Actuator Series

M-Series or R-Series



Actuator Part Number

Refer to part number breakdown for available options.

QR Code

Scan this QR code for a direct link to the user manual for your unit!

Actuator Serial Number

This serial number is unique for each individual unit and is directly tied to your order/invoice number.